## **Chaos in Kuramoto Oscillator Networks**

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## Abstract

Kuramoto oscillators are widely used to explain collective phenomena in networks of coupled oscillatory units. We show that simple networks of two populations with a generic coupling scheme can exhibit chaotic dynamics as conjectured by Ott and Antonsen [Chaos, 18, 037113 (2008)]. These chaotic mean field dynamics arise universally across network size, from the continuum limit of infinitely many oscillators down to very small networks with just two oscillators per population. Hence, complicated dynamics are expected even in the simplest description of oscillator networks.

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The Kuramoto phase model [1] and its generalization by Sakaguchi [2] are widely used to understand synchronization and other collective phenomena in weakly coupled oscillator networks in physics and biology [3]. Networks of globally coupled Kuramoto oscillators cannot exhibit chaotic dynamics if the oscillators are identical due to degeneracy [4]. Moreover, phase chaos for globally coupled nonidentical units vanishes in the continuum limit of infinitely many oscillators [5]. Hence, a decade ago, Ott and Antonsen conjectured in their seminal paper [6] that networks of two or more populations—where interactions are all-to-all but distinct between and within populations—could exhibit chaotic mean-field dynamics, both in the continuum limit and in finite networks. So far, however, only periodic and quasiperiodic motions of the mean field have been observed for coupled populations of Kuramoto oscillators [7, 8].

In this paper we report chaotic mean field dynamics for two populations of N Kuramoto phase oscillators. More specifically, we consider oscillator networks where the phase  $\theta_{\sigma,k} \in \mathbf{T} := \mathbb{R}/2\pi\mathbb{Z}$  of oscillator  $k \in \{1, \dots, N\}$  in population  $\sigma \in \{1, 2\}$  evolves according to

$$\dot{\theta}_{\sigma,k} = \omega_{\sigma,k} + \sum_{\tau=1}^{2} \frac{K_{\sigma\tau}}{N} \sum_{j=1}^{N} \sin(\theta_{\tau,j} - \theta_{\sigma,k} - \alpha_{\sigma\tau}); \tag{1}$$

the intrinsic frequencies  $\omega_{\sigma,k}$  are sampled from a Lorentzian distribution with half-width-at-half-maximum  $\Delta$  [9] and  $K_{\sigma\tau}$  and  $\alpha_{\sigma\tau}$  are the coupling strength and phase-lag between populations  $\sigma$  and  $\tau$ . While (1) has been extensively studied for networks with identical phase-lags  $\alpha_{\sigma\tau} = \alpha$  [2, 6, 7, 10], we find here that chaotic dynamics arise in the generic situation where both coupling strength  $K_{\sigma\tau}$  and phase-lags  $\alpha_{\sigma\tau}$  are distinct [11]. Chaotic mean field dynamics appear in the continuum limit  $N \to \infty$  as well as finite-dimensional networks (1), down to networks of just N=2 oscillators per population. First, our results provide a positive answer to Ott and Antonsen's conjectures for minimal networks of two populations. Second, neither heterogeneity, amplitude variations, the influence of fast oscillations, nonautonomous forcing, nor higher-order interactions are necessary to observe chaos. Hence, we anticipate that such chaotic phase dynamics arise in a large number of real-world systems [12, 13].

Chaotic Mean Field Dynamics in the Continuum Limit.—Each oscillator of the network (1) is driven by a common mean field which depends on the Kuramoto order parameter

$$Z_{\sigma} = r_{\sigma}e^{i\phi_{\sigma}} = \frac{1}{N} \sum_{j=1}^{N} e^{i\theta_{\sigma,j}}$$
 (2)

of population  $\sigma$ ; here  $i=\sqrt{-1}$ . The order parameter encodes the level of synchrony of the population:  $|Z_{\sigma}|=r_{\sigma}=1$  if and only if population  $\sigma$  is fully phase synchronized. Write  $\alpha_s:=$ 

 $\alpha_{\sigma\sigma}$ ,  $k_s:=K_{\sigma\sigma}$  for the self-coupling strength and phase-lag, and  $k_n:=K_{12}=K_{21}$ ,  $\alpha_n:=\alpha_{12}=\alpha_{21}$  for the neighbor-coupling strength and phase-lag. By rescaling time appropriately we set  $k_s+k_n=1$  and parametrize the deviation  $A=k_s-k_n$  of coupling strengths. This yields the complex coupling parameters  $c_s=c_s(\alpha_s,A):=k_se^{-i\alpha_s}$ ,  $c_n=c_n(\alpha_n,A):=k_ne^{-i\alpha_n}$ . Now

$$H_{\sigma} = c_s Z_{\sigma} + c_n Z_{\tau},\tag{3}$$

with  $\tau=2$  if  $\sigma=1$  and  $\tau=1$  if  $\sigma=2$ , drives the evolution of population  $\sigma$  since (1) can be rewritten as

$$\dot{\theta}_{\sigma,k} = \omega_{\sigma,k} + \operatorname{Im}(H_{\sigma}e^{-i\theta_{\sigma,k}}). \tag{4}$$

In the continuum limit, the system (4) is described by the evolution of the probability density  $f_{\sigma}(\theta,t)$  for an oscillator of population  $\sigma$  to be at  $\theta \in \mathbf{T}$  at time t. In the limit, the order parameter (2) of population  $\sigma$  is  $Z_{\sigma}(t) = r_{\sigma}(t)e^{i\phi_{\sigma}(t)} = \int_{0}^{2\pi} e^{i\theta}f_{\sigma}(\theta,t)\mathrm{d}\theta$ . Let  $\bar{w}$  denote the complex conjugate of  $w \in \mathbb{C}$ . Ott and Antonsen [6] showed that there is an invariant manifold of  $f_{\sigma}(\theta,t)$  on which the dynamics are determined by

$$\dot{Z}_{\sigma} = -\Delta Z_{\sigma} + \frac{1}{2}H_{\sigma} - \frac{1}{2}\bar{H}_{\sigma}Z_{\sigma}^{2}.$$
 (5)

Since these equations are symmetric by shifting phases by a constant angle, we introduce the phase difference  $\psi = \phi_1 - \phi_2$  to obtain the three-dimensional system

$$\dot{r}_1 = -\Delta r_1 + \frac{1 - r_1^2}{2} (r_1 \operatorname{Re}(c_s) + r_2 \operatorname{Re}(\bar{c}_n e^{-i\psi}), \tag{6a}$$

$$\dot{r}_2 = -\Delta r_2 + \frac{1 - r_2^2}{2} (r_2 \operatorname{Re}(c_s) + r_1 \operatorname{Re}(\bar{c}_n e^{i\psi}), \tag{6b}$$

$$\dot{\psi} = \frac{1 + r_1^2}{2r_1} \left( r_1 \operatorname{Im}(\bar{c}_s) + r_2 \operatorname{Im}(\bar{c}_n e^{-i\psi}) \right) - \frac{1 + r_2^2}{2r_2} \left( r_2 \operatorname{Im}(c_s) + r_1 \operatorname{Im}(\bar{c}_n e^{i\psi}) \right). \tag{6c}$$

with  $0 < r_1, r_2 \le 1$ ,  $\psi \in [0, 2\pi)$ . The equilibrium  $SS_0 = (1, 1, 0)$  corresponds to full (phase) synchrony,  $SS_{\pi} = (1, 1, \pi)$  to a two cluster solution where the clusters are in anti-phase, and I = (0, 0, \*) denotes completely incoherent configurations with  $Z_1 = Z_2 = 0$ . Moreover, there is a time-reversal symmetry for  $(\alpha_s, \alpha_n) = (\frac{\pi}{2}, 0)$ ; cf. [11] for details.

Chaotic attractors arise in the mean field dynamics (6) of the continuum limit; here we fix A=0.7 but there is a range of A for which there are chaotic dynamics; Fig. 1. Consider identical oscillators,  $\Delta=0$ . The bifurcation diagram in Fig. 1(a) shows that the attractors arise through a period-doubling cascade. They are subsequently destroyed as they approach the invariant surfaces

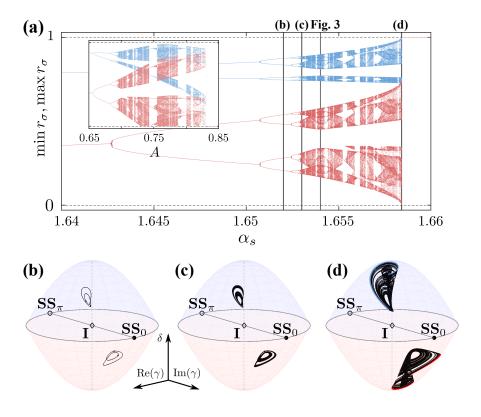


Figure 1. Chaotic attractors arise for the mean field dynamics (6) for A=0.7 and fixed  $\alpha_n=0.44$ . Panel (a) shows the local maxima and minima of  $r_\sigma=|Z_\sigma|$ ; chaos arises through a period doubling cascade and the chaotic attractor is destroyed as it approaches the invariant surface  $r_\sigma=1$  (dashed) and  $r_\sigma=0$  (dashed). In the inset A is varied as  $\alpha_s=1.654$  is fixed. Initial conditions were continued quasi-adiabatically as parameters are varied. Panels (b–d) show trajectories (black curves) for the parameter values highlighted in (a) by black vertical lines in the projection  $(\gamma,\delta)=(Z_1\bar{Z}_2,|Z_1|^2-|Z_2|^2)$ : (b) after the second period doubling,  $\alpha_s=1.652$ , (c) after the fist transition to chaos,  $\alpha_s=1.653$ , and (d) just before the crisis,  $\alpha_s=1.6584$ . Invariant surfaces for  $r_1=1$  (blue) and  $r_2=1$  (red) intersect in the unit circle (gray). Points on the attractor in close proximity to the invariant surfaces are highlighted in the color of each surface.

 $r_{\sigma}=1$  where one of the populations is phase synchronized. The system symmetry  $(r_1,r_2,\psi)\mapsto (r_2,r_1,-\psi)$  implies the existence of two attractors which are related by symmetry. Hence, there is multistability of the fully synchronized equilibrium  $SS_0$  and two chaotic attractors. Note that the phase difference of the mean fields  $\psi$  is bounded (see Fig. 1(b–d)), that is, the centroids of the order parameters  $Z_{\sigma}$  do not rotate relative to one another.

To quantify the chaotic dynamics we calculate the maximal Lyapunov exponents  $\lambda_{\text{max}}$  for the mean field equations (6). Fig. 2 shows a region in  $(\alpha_s, \alpha_n)$ -parameter space where the maximal

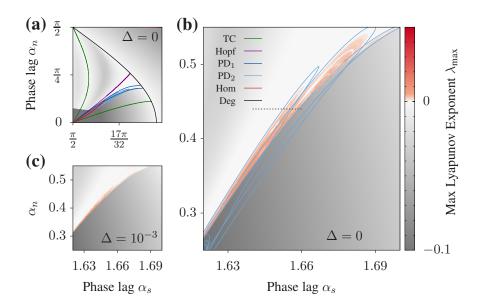


Figure 2. The mean field equations (6) show positive Lyapunov exponents (coloring) in a region of  $(\alpha_s, \alpha_n)$ -parameter space for A=0.7. The system was integrated numerically from the fixed initial condition  $(r_1(0), r_2(0), \psi(0)) = (0.8601, 0.4581, 1.1815)$ . Panel (a) shows the maximal Lyapunov exponents overlaid with two-parameter bifurcation lines: the transcritical (TC), Hopf, and first period-doubling (PD<sub>1</sub>) lines emanate from  $(\alpha_s, \alpha_n) = (\frac{\pi}{2}, 0)$  and end in the degenerate bifurcation (Deg) where  $SS_0$  and  $SS_{\pi}$  swap stability [11]. Panel (b) shows a magnification of the region where positive Lyapunov exponents arise (red color); a dotted line indicates the parameter range shown in Fig. 1. Chaotic regions are bounded by "lobes" of second period-doubling PD<sub>2</sub> lines. Panel (c) shows that positive Lyapunov exponents persist for nonidentical oscillators with a nontrivial distribution of intrinsic frequencies  $\Delta > 0$ .

Lyapunov exponents are positive. Numerical continuation of the bifurcations shown in Fig. 1 in the parameter plane using AUTO [14] shows that the chaotic region is organized into multiple "lobes" which are bounded by period-doubling curves (PD<sub>2</sub> in Fig. 2). Moreover, multiple bifurcation lines—including period doubling and a homoclinic bifurcation—end in the point  $(\alpha_s, \alpha_n) = (\frac{\pi}{2}, 0)$  where the system has a time-reversal symmetry. Hence, these parameter values appear to organize the bifurcations.

Note that the chaotic region persists in the continuum limit for non-identical oscillators,  $\Delta > 0$ ; cf. Fig. 2(c).

Chaotic Dynamics for Finite Networks.—The dynamics of finite networks (1) of N > 3 identical oscillators,  $\omega_{\sigma,k} = \omega$ , can be described exactly in terms of collective variables [4, 15, 16]. (We assume  $\omega = 0$  without loss of generality.) Then the phase space  $\mathbf{T}^{2N}$  of (1) is foliated by six-

dimensional leafs, each of which is determined by constants of motion  $\psi_k^{(\sigma)}$ ,  $k=1,\ldots,N$  (N-3) are independent. The dynamics of population  $\sigma=1,2$  on each leaf are given by the evolution of its bunch amplitude  $\rho_\sigma$ , bunch phase  $\Phi_\sigma$ , and phase distribution variable  $\Psi_\sigma$ . Write  $z_\sigma=\rho_\sigma e^{i\Phi_\sigma}$ . The bunch variables relate to the order parameter (2) through  $Z_\sigma=z_\sigma\gamma_\sigma$  where

$$\gamma_{\sigma} = \frac{1}{N\rho_{\sigma}} \sum_{j=1}^{N} \frac{\rho_{\sigma} e^{i\Psi_{j}} + e^{i\psi_{j}^{(\sigma)}}}{e^{i\Psi_{\sigma}} + \rho_{\sigma} e^{i\psi_{j}^{(\sigma)}}}.$$

Now (3) evaluates to  $H_\sigma=c_sz_\sigma\gamma_\sigma+c_nz_\tau\gamma_\tau$  and the oscillator bunch evolves according to

$$\dot{\rho}_{\sigma} = \frac{1 - \rho_{\sigma}^2}{2} \operatorname{Re}(H_{\sigma} e^{-i\Phi_{\sigma}}), \tag{7a}$$

$$\dot{\Phi}_{\sigma} = \frac{1 + \rho_{\sigma}^2}{2\rho_{\sigma}} \operatorname{Im}(H_{\sigma}e^{-i\Phi_{\sigma}}), \tag{7b}$$

$$\dot{\Psi}_{\sigma} = \frac{1 - \rho_{\sigma}^2}{2\rho_{\sigma}} \operatorname{Im}(H_{\sigma}e^{-i\Phi_{\sigma}}). \tag{7c}$$

(The dynamics of individual oscillators (1) is determined by (7) through (4) and (3).) Note that  $\gamma_{\sigma} \to 1$  (and thus  $z_{\sigma} \to Z_{\sigma}$ ) as  $N \to \infty$  if the constants of motion are uniformly distributed on the circle,  $\psi_k^{(\sigma)} = 2\pi k/N$ , as shown in [16]; in this case we recover (5) as (7c) decouples from (7a) and (7b).

Chaotic dynamics arise in networks of finitely many identical Kuramoto oscillators (1) for a wide range of system sizes. We fix phase-lags  $\alpha_s$ ,  $\alpha_n$  while varying N and take the constants of motion be uniformly distributed on the circle,  $\psi_k^{(\sigma)} = 2\pi k/N$ . The dynamics are now given by (7); effectively, these are the mean field dynamics of the continuum limit (6) modulated by finite-size fluctuations through  $\gamma_\sigma$  (which depend on  $\Psi_\sigma$  and vanish as  $N \to \infty$ ). Fig. 3(a,b) show chaotic dynamics similar to those of the continuum limit (cf. Fig. 1) for N=20 oscillators per population. Numerical calculation of maximal Lyapunov exponent for varying system size, shown in Fig. 3(c), indicate that there are not only chaotic dynamics for any network of  $N \ge 20$  oscillators per population, but also for small networks.

The chaotic dynamics persist as the initial conditions are varied in the full system (1). Keeping the constants of motion fixed will keep us on the same leaf of the foliation. But a generic perturbation of an initial conditions in the full system (1) will be on a different leaf of the foliation. To explore the dynamics for nearby leafs—and thus nearby initial conditions in (1)—we parametrize the constants of motion by  $s \ge 0$  by setting  $\psi_k^{(\sigma)} = 2s\pi k/N$ . Note that for s = 1 we have a uniform distribution as above. Fig. 3(d-f) show the dynamics for varying parameter s for a network

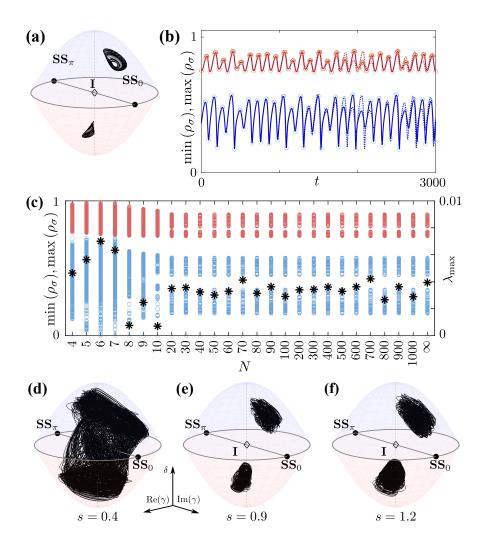


Figure 3. Finite Kuramoto oscillator networks (7) show robust chaos as the system size N and constants of motion, parametrized by s, are varied; here A=0.7,  $\alpha_n=0.44$ ,  $\alpha_s=1.654$  (see Fig. 1). Panel (a) shows a trajectory of (7) for N=20, s=1 in the projection  $(\gamma,\delta)=(z_1\bar{z}_2,|z_1|^2-|z_2|^2)$ . Panel (b) illustrates how the trajectory in (a) (solid,  $\rho_1=|z_1|$  red,  $\rho_2=|z_2|$  blue) diverges from the dynamics of  $|Z_\sigma|$  (dashed) in the continuum limit (6). Minima/maxima of fast finite size oscillations are highlighted (light blue/red circles). The observed chaotic dynamics is robust in s and s: Panel (c) shows local minima/maxima in  $|z_1|$  and  $|z_2|$  (circles in Panel (a)) and maximal Lyapunov exponent s (asterisks) for varying network size s (s = 1 fixed). Panels (d-f) show chaotic dynamics for s = 20 as the constants of motion are varied with s.

of N=20 oscillators per population. This suggests that even in small networks chaotic dynamics arise for many initial conditions.

There is further evidence that the mechanism that generates the chaotic dynamics is universal across system sizes, even where the mean field reductions cease to apply. For nearby parameter

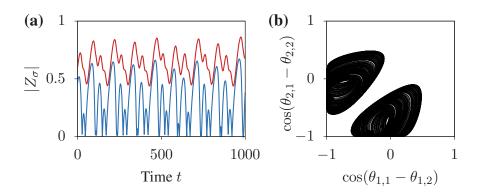


Figure 4. Attracting chaos arises in oscillator networks (1) of two populations of N=2 oscillators for parameters A=0.7,  $\alpha_s=1.639$ , and  $\alpha_n=0.44$ . Panel (a) shows the evolution of the order parameter over time. Panel (b) shows the phase evolution in a two-dimensional projection and a symmetric image.

values we find persistent chaos for two populations of N=2 oscillators each; cf. Fig. 4. This is the smallest network of two populations in which chaos can occur since the phase-space is effectively three-dimensional. These solutions are chaotic weak chimeras [17–19]. Hence our results also show that chaotic weak chimeras can occur even in the simplest system through symmetry breaking. A full analysis of this small system is beyond the scope of this manuscript and will be published elsewhere.

Discussion.—Chaotic dynamics can—as conjectured by Ott and Antonsen [6]—indeed arise in two populations networks of coupled Kuramoto phase oscillators. Remarkably, these chaotic dynamics appear not only in the continuum limit and in large populations, but for roughly the same parameter values also in the smallest possible networks. While chaos has been observed in spatially extended (infinite-dimensional) mean field equations [20], the setup of two populations is the smallest system possible in which chaos can arise in the mean field for Kuramoto oscillators. Moreover, the chaotic dynamics here are distinct from chaos in systems where interaction depends explicitly on the oscillators' phases (rather than the phase differences) [15, 21] since they have additional degrees of freedom. As in [22], chaos appears to relate to parameter values where the system has a time-reversal symmetry [23]. Hence this raises the questions whether the symmetry induces suitable homoclinic or heteroclinic structures whose breaking yields attracting chaos across system sizes.

Our results show that—in contrast to phase chaos [5]—there is chaos in the continuum limit for identical and almost identical oscillators as given by the Ott–Antonsen reduction (5). At the same time, we showed chaotic dynamics are also present in finite networks of identical oscillators

whose dynamics are given by the Watanabe–Strogatz equations (7). Neither of these approaches yields a suitable description of the finite-size networks of nonidentical oscillators; cf. also [24]. Is there chaos for finite networks of non-identical oscillators ( $\Delta > 0$ )? And if so, what are its properties, for example, the dimension of the attractor? Recently, perturbation theory has proved useful to describe the evolution of trajectories for near-integrable systems [25], but new techniques are called for to describe the collective dynamics of nonidentical oscillator networks with respect to both the integrable case and the continuum limit.

In summary, oscillator networks (1) with simple sinusoidal interactions have surprisingly rich dynamics. For two populations of oscillators, higher-order effects such as amplitude variations or the influence of the fast oscillations, are not required to observe chaotic dynamics. Hence, we anticipate chaotic fluctuations to arise in small experimental oscillator setups [12, 13]. Moreover, we expect much richer dynamics for three or more populations of phase oscillators [26]. Such multi-community oscillator networks have been instructive to understand the dynamics of neural synchrony patterns [27, 28], where distributed phase-lags are of particular importance due to the finite speed of signal propagation. Distributed phase-lags give rise to chaotic dynamics and we therefore anticipate that our results further illuminate the dynamics of large-scale (neural) oscillator networks.

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